

ABSTRACT OF THE DISCLOSURE

Disclosed is a surgical arm system for holding and positioning one or more instruments during a surgical procedure. The surgical arm includes at least one quick connect mechanism that beneficially allows for simple and expeditious, yet reliable disassembly and reassembly of the arm by any member of a surgical team without difficulty and without requiring additional tools, but while still ensuring that, following reassembly, the arm is structurally sound, properly dimensioned, and capable of functioning in a highly reliable manner.

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